



# SHELF-READING ROBOT SYSTEM



A member of HKC  
International Holdings  
Limited (HKG:248)

# Tooker Robot Core Features

1. **Trackless autonomous navigation:** The robot uses Lidar to navigate independently without the need to modify the existing environment.
2. **Adaptive navigation obstacle avoidance:** During the robot's journey, it can adaptively detect obstacles and avoid collisions with them.
3. **Accurate book localization:** Based on RFID sensing, centimeter-level book positioning is achieved, helping library staff locate mis-shelved books.
4. **Lost/ Missing book inventory:** Able to quickly inventory for lost books, achieving efficient and book management accurate.
5. **Automatic charging function:** With automatic charging function to ensure uninterrupted continuous work.



## Product Models



UHF Robot



HF Robot



Hybrid Robot

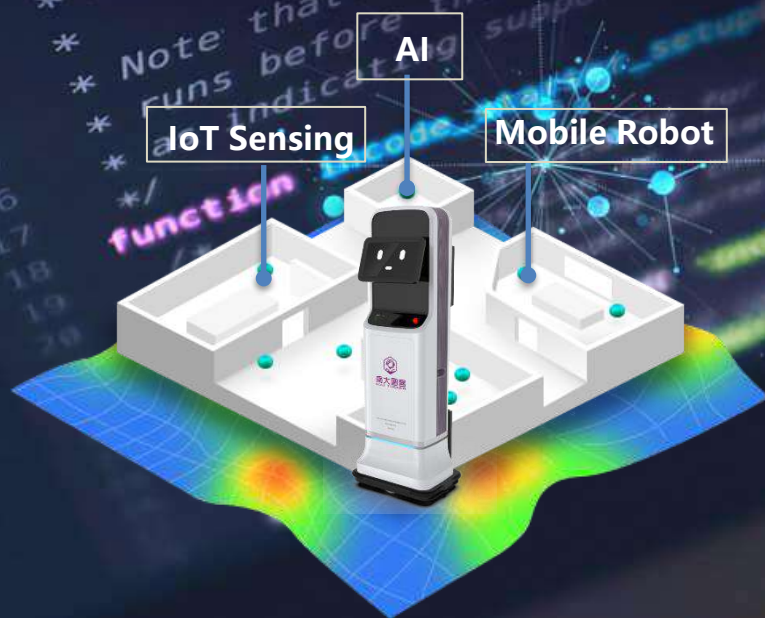


CV Robot

Detection Rate: **99%**

Localization Accuracy: **96%**

# Core Technology



Tooker combines Internet of Things (IoT) sensing technology, artificial intelligence technology, and mobile robot technology to achieve automated book inventory and positioning.



## Book Localization

Accurate book positioning based on RFID technology.



## Autonomous Navigation

Navigation combined with RFID and LiDAR



## Obstacle Avoidance

Multi-modal Obstacle Avoidance



## Core Advantage 1: Accurate UHF RFID Localization

Reading Distance  
10 Meters

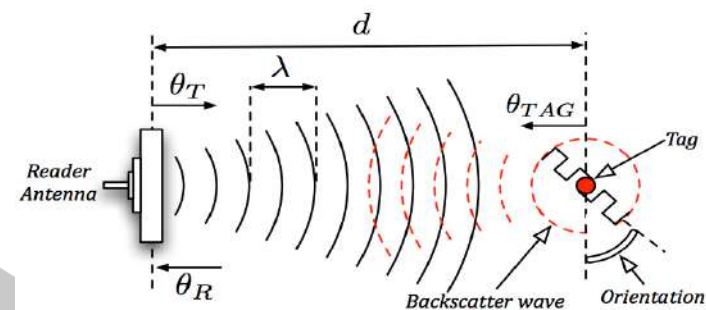
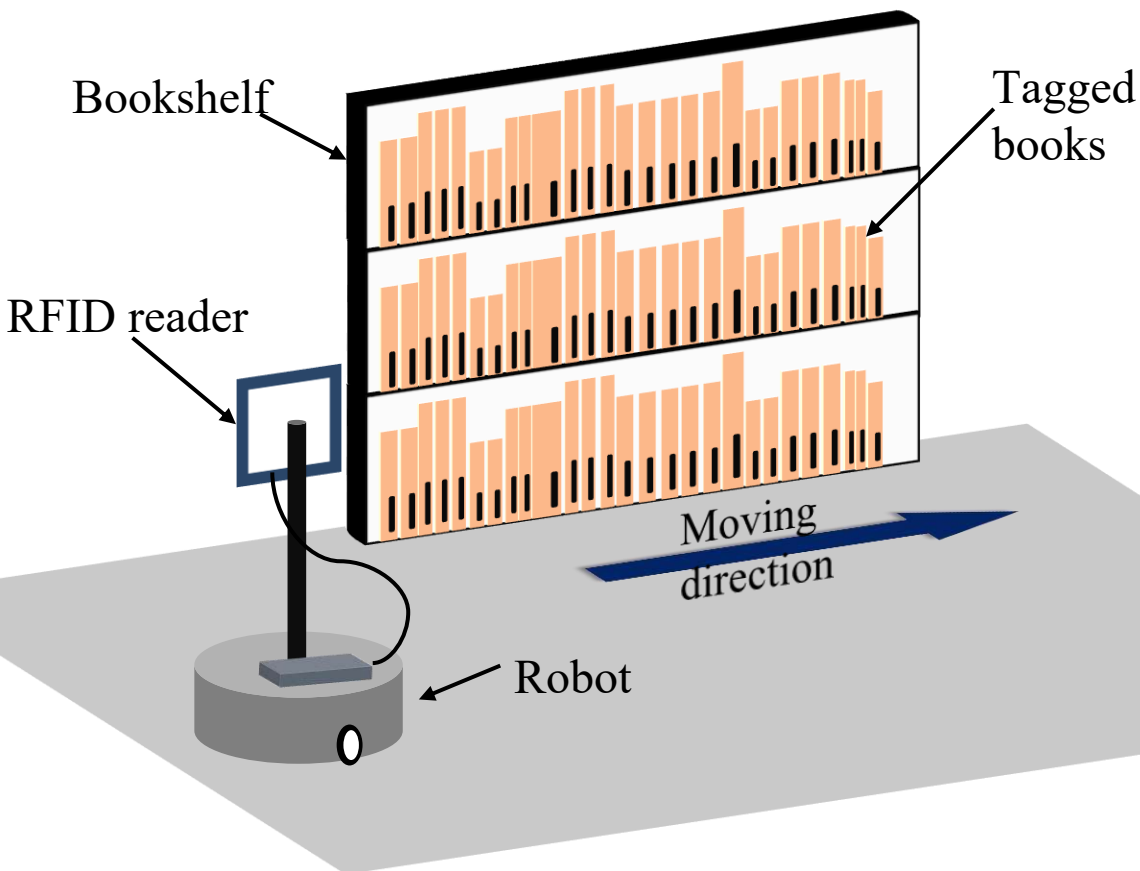
Granularity of  
positioning  
cm

Technical Challenges

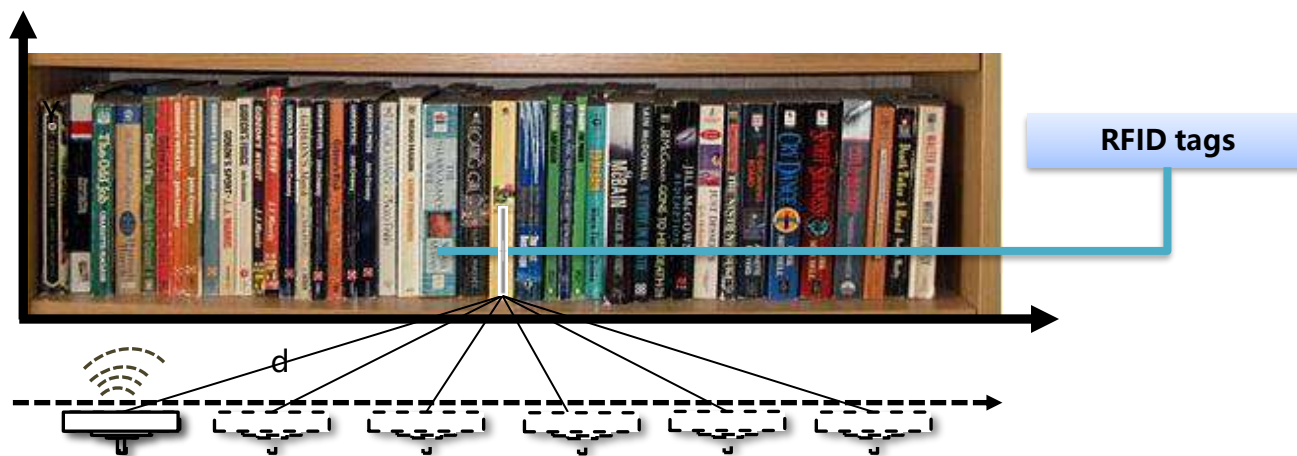
How to accurately locate each  
book in Library



## Core Advantage 1: Accurate UHF RFID Localization



## Core Advantage 1: Accurate UHF RFID Localization



"Phase + Hyperbola" Mode

$$d = \sqrt{(a - vt)^2 + b^2}.$$

$$\theta = \frac{4\pi}{\lambda} \sqrt{(a - vt)^2 + b^2} + \mu.$$



$$\frac{(\theta - \mu)^2}{\left(\frac{4\pi}{\lambda}\right)^2 b^2} - \frac{\left(t - \frac{a}{v}\right)^2}{\frac{b^2}{v^2}} = 1$$

International top-tier conference paper : **IEEE INFOCOM**

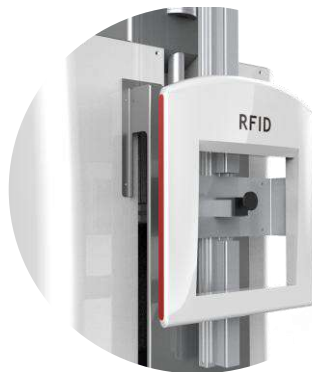
## Core Advantage 2 : HF RFID (High detection rate)



(General Market Problem)

Low detection rate: Low transmit power & impedance mismatch

### Tooker's HF RFID Technology



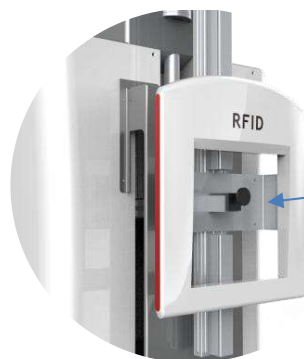
Self-designed HF RFID **readers**



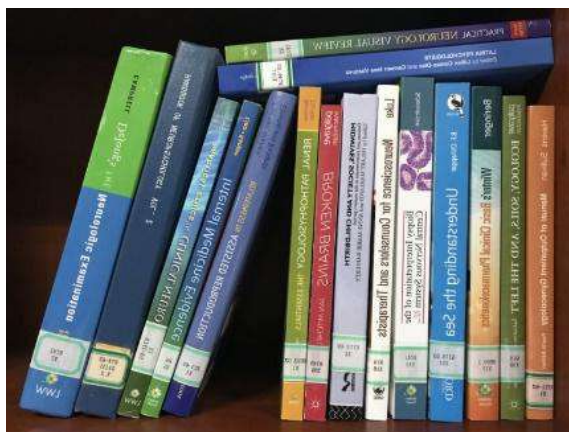
Self-designed HF RFID **antennas**



## Core Advantage 3 : Computer Vision



Camera



Scan and input Image



Book Spine Segmentation

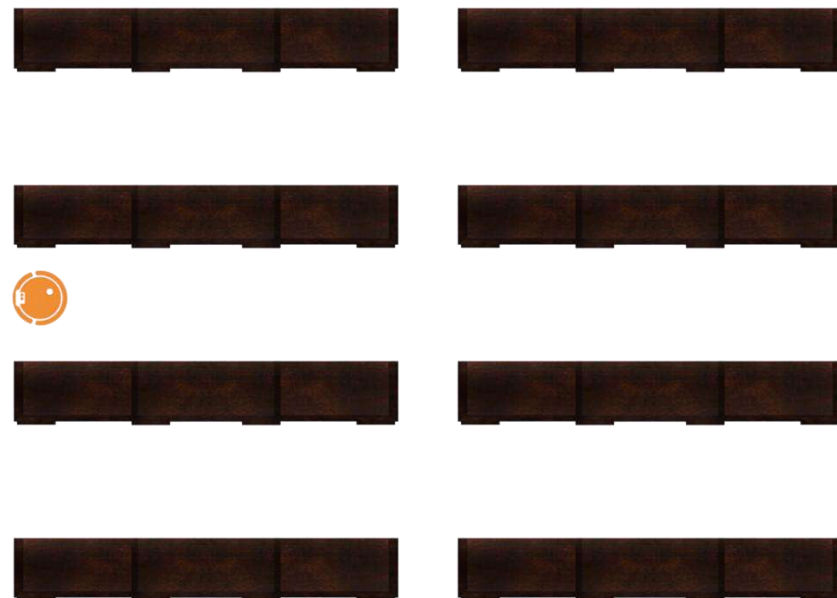


Book title and call number  
recognition algorithm

**Au**



## Core Advantage 4 : Two Lidars



**Help the robot better navigate and detect obstacles**

## Core Advantage 5 : Two Independent Lifting Systems



Chinese Patent

Suitable for different shelf sizes, automatically adjusting according to shelf height



## Core Advantage 6 : Quiet Book Inventory



**Brushless Motor**

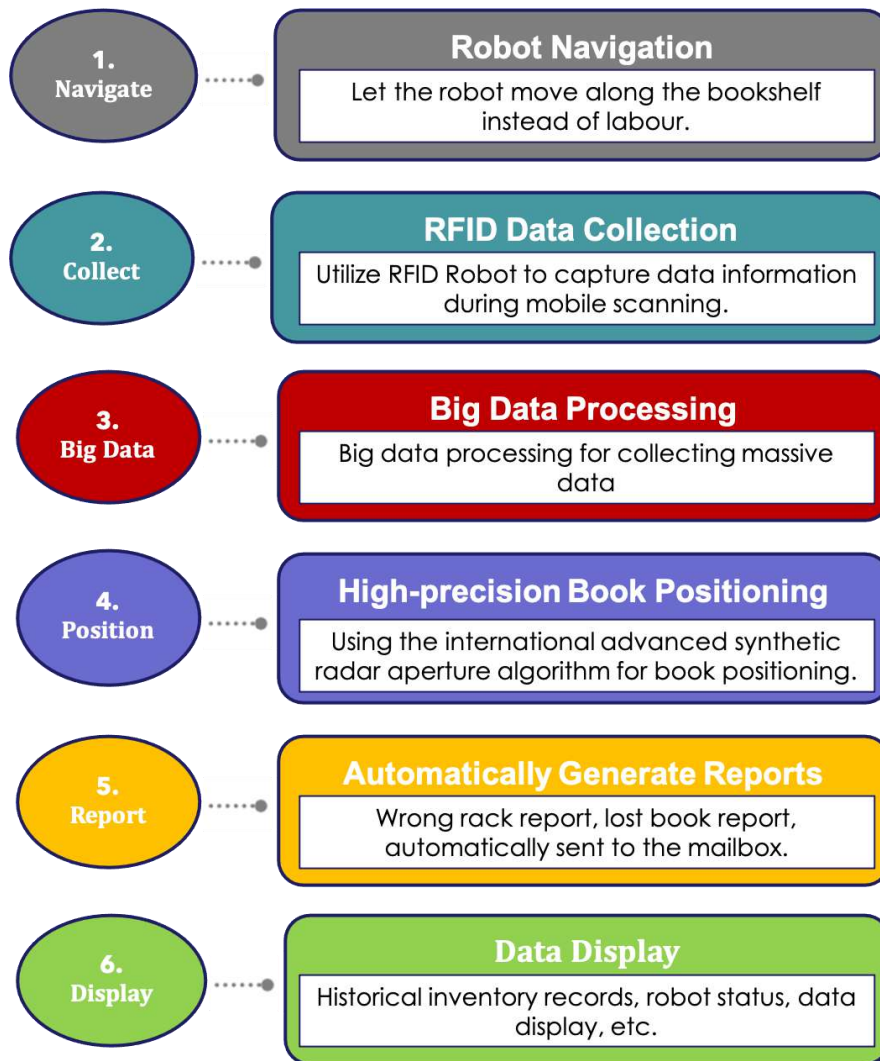


**Quiet drive wheel**

**People can hardly hear any noise when Tooker runs.**



## Robot Technical Architecture Diagram



## Tooker's Robot Specification Parameters

Tooker Shelf-reading Robot Hardware Parameters and Performance		
1	External Dimensions	L580m * W490mm * H1680mm
2	Upper Computer Configuration	Intel Core i5 Dual Core CPU + 8G memory, 256G or above solid-state hard drive
3	Lower Computer Configuration	Intel NUC6i5SYH
4	Traction Motors	2 Brushless DC motors
5	Display Screen Size	15.6-inch touch LCD
6	RFID Working Frequency	860Mhz-960MHz: Ultra-high frequency. 13.56MHz: High Frequency. Comply with ISO18000-6C, ISO15963 standard Equipped with dual camera module for visual assistance in inventory management.
7	Dual Lift Rod Module	<ul style="list-style-type: none"> <li>2 independent lift systems (suitable for different shelf sizes, automatically adjusting according to shelf height). <ul style="list-style-type: none"> <li>Lower lift rod stroke: 180-990mm.</li> <li>Upper lift rod stroke: 1170-2250mm</li> </ul> </li> </ul>
8	Dual Laser Radar Module	Equipped with at least two laser radars in the forward and backward directions, for bidirectional navigation between shelves.

**Tooker Shelf-reading Robot Hardware Parameters and Performance**

9	Wheel System Characteristics	Mobile chassis with differential wheel structure, ensuring quietness during inventory management: active wheels with suspension shock absorption structure, ensuring smooth mobility.
10	Maximum Speed of Book Inventory Robot	0.5m/s
11	Speed Resolution	0.01m/s
12	Battery Working Time	Continuous running time of not less than 9 hours
13	Charging Time	6 hours
14	Operating Noise	Less than 40 decibels (1 meter from inventory machine)
15	International Standards	Conform to ISO18000-6C, ISO15963 standards
16	Self-Charging	When the battery is low, it should automatically return to the charging station for self-charging.
17	Two-Way Communication	Book inventory robot has two-way data communication with the backend server.
18	Manual Emergency Stop	In case of malfunction, there is a manual emergency stop function.

## Main Functions

1. Accuracy of Book Level Positioning
2. Book Sorting Accuracy
3. Book Inventory Efficiency
4. Report Data
5. Auto-charging
6. Night stocktake
7. Protruding Book Obstacle Avoidance
8. Stocktake Mode
9. Robot Operation Sound
10. System Docking
11. Support Zero Cost Shelf Function
12. Alarm Function





# Project Experiences



65 Sites

## School Library

**University & College /24 Sites**

The Chinese University of Hong Kong (Shenzhen) | Wuhan University | Nanjing University | Sun Yat-sen University | Tongji University | Guangzhou International Campus of South China University of Technology | Nanjing University of Aeronautics and Astronautics | China Agricultural University | East China Normal University | Shenzhen University | Hunan University of Science and Technology | Wuhan Polytechnic University | Zhejiang International Studies University | Xi'an Jiaotong-Liverpool University | Chengdu University | Shandong First Medical University | Huaibei Normal University | Sichuan Conservatory of Music | University of South China | Tongling University | Xiamen University | Beijing Normal University | Hebei Normal University | Chengdu University of Technology.

**High School /4 Sites**

Shanghai Luwan Senior High School | Shanghai Shibei Junior Middle School | Nanjing No.1 High School | Taiyuan Second Foreign Language School

**Vocational College /3 Sites**

Shanghai News and Press College | Chongqing Engineering Vocational and Technical College | Anyang Preschool Teacher's College

**Military academies /3 Sites**

Army Engineering University | Rocket Force Engineering University | Xi'an Armed Police Engineering University

## Public Library

**Provincial /3 Sites**

Shanghai Library | Nanjing Library | Hainan Provincial Library.

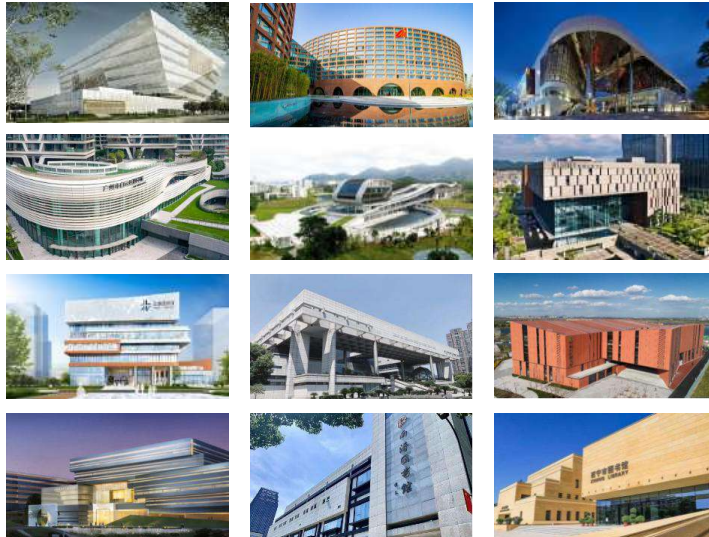
**City /11 Sites**

Nantong City Library | Hefei Central Library | Huzhou Library | Bengbu Library | Yuyao City Library | Tangshan City Library | Shijiazhuang City Library | Xining City Library | Guiyang Children's Library | Liaocheng City Library | Jinan City Library

**District /17 Sites**

Shanghai Huangpu District Library | Suzhou Wuzhong District Library | Guangzhou Baiyun District Library | Guangzhou Yuexiu District Library | Kunshan City Library | Guangzhou Huadu District Library | Guangzhou Huangpu District Library | Shenzhen Bao'an District Library | Shenzhen University City Library | Yixing City Library | Wuhan Dongxihu Cultural Center Library | Tianjin China-Singapore Friendship Library | Huzhou Nanxun Library | Ningbo University Campus Library | Shanghai Xuhui District Library | Guangzhou Panyu District Library | Ningbo Beilun District Library

# References Site



The Tooker smart book inventory robot is being applied in public libraries across the country, including libraries in major cities such as Beijing, Shanghai, Guangzhou and Shenzhen, as well as libraries in various provinces, cities, districts and counties.

This includes major universities, public libraries, military academies, K12 schools and other users across the country.











# Sample UI



# Dashboard

报表管理平台

图客超管

Home

Robot

Library

Report Data

Visualization Add

Visualization

Account

Account



Robot List



Report List



Visualization



Account Center

Total Library

0



Total Robots

4



Total Report

0



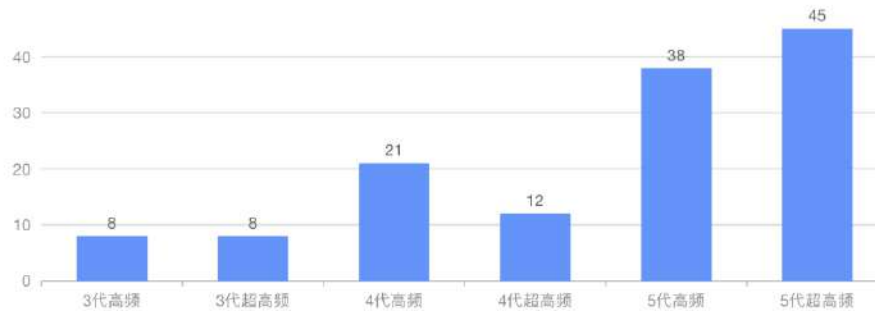
Total Time

.00



Robot Model

more



Latest Report

more

Singapore demo project, 4th floor, Report data

2023-03-03 15:23:00

Singapore demo project, 4th floor, Report data

2023-03-03 15:06:17

Singapore demo project, 4th floor, Report data

花都区图书馆, 6楼, 报表数据 2023-03-03 15:00:08

花都区图书馆, 7楼, 报表数据 2023-03-03 10:26:04

2023-03-03 05:28:17

深圳大学城图书馆, 2楼, 报表数据

# Robot List

报表管理平台

图客超管

Home

Robot

Robot Add

Robot List

Heart Log

Robot Notice

Library

Report Data

Visualization Add

Visualization

Account

Account

≡

Robot / Robot List

## Robot List

App Id:

Name:

Reset

Query

Expand

Index	App Id	Name	Category	State	Create Time
1	qKYTjtey03a9vc2	上图01	NJU-RS-AU5	Closing	2022-08-05 15:40:26
2	jmEQQI0JIDgP15J	上图02	NJU-RS-AU5	Closing	2022-08-05 15:40:26
3	bVXf0k1pUdBuScd	上图03	NJU-RS-AU5	Closing	2022-08-05 15:40:26
4	pbgJTuzYHhAeKV	上图04	NJU-RS-AU5	Closing	2022-08-05 15:40:26
5	InHzXpC7d5LBvHh	上图05	NJU-RS-AU5	Closing	2022-08-05 15:40:26
6	IGByVbiIJ1PcN7u	上图06	NJU-RS-AU5	Closing	2022-08-05 15:40:26
7	it8Fhjq6AU98gsD	上图07	NJU-RS-AU5	Closing	2022-08-05 15:40:26
8	Ww488G0TuLwSqu	上图08	NJU-RS-AU5	Closing	2022-08-05 15:40:26
9	7g7xzgzY87lveuB	花都-6楼a	NJU-RS-AU5	Closing	2022-08-08 17:47:23

# Job Completed Status

报表管理平台

图客超管

Home

Robot

Robot Add

Robot List

Heart Log

Robot Notice

Library

Report Data

Visualization Add

Visualization

Account

Account

Menu

Robot / Heart Log

## Heart Log

App Id:

Name:

Reset

Query

Expand

Index	App Id	Name	Create Time	State
1	L6TRL84Xy0uPb7m	华师大闵行-2/5楼	2023-03-03 19:41:55	成功
2	UPqupxtf3xUyRVO	白云2楼	2023-03-03 19:41:51	成功
3	aTXbox5jThdZKdB	四川音乐学院	2023-03-03 19:41:03	成功
4	L6TRL84Xy0uPb7m	华师大闵行-2/5楼	2023-03-03 19:40:55	成功
5	UPqupxtf3xUyRVO	白云2楼	2023-03-03 19:40:51	成功
6	aTXbox5jThdZKdB	四川音乐学院	2023-03-03 19:40:03	成功
7	L6TRL84Xy0uPb7m	华师大闵行-2/5楼	2023-03-03 19:39:54	成功
8	UPqupxtf3xUyRVO	白云2楼	2023-03-03 19:39:51	成功
9	aTXbox5jThdZKdB	四川音乐学院	2023-03-03 19:39:02	成功



# Visualization

## Visualization






Name: 

Update Time: 

Reset

Query

### 高级表格

Index	Name	Url	Update Time	Operate
1	大屏可视化		2022-06-14 15:53:00	<a href="#">Preview</a> <a href="#">修改</a> <a href="#">删除</a>
2	上海图书馆		2022-08-15 14:13:06	<a href="#">Preview</a> <a href="#">修改</a> <a href="#">删除</a>
3	同济大学图书馆		2022-08-26 15:21:17	<a href="#">Preview</a> <a href="#">修改</a> <a href="#">删除</a>
4	华东师范大学		2022-09-21 14:47:22	<a href="#">Preview</a> <a href="#">修改</a> <a href="#">删除</a>
5	南通市图大屏		2022-12-07 09:44:33	<a href="#">Preview</a> <a href="#">修改</a> <a href="#">删除</a>

1-5 of 5 items &lt; 1 &gt;



# Visualization Report

## 盘点报告

🕒 2023-03-03 19:58:49

总数 **24,288**

2023-03-02 报表汇总

TAG异常 **495**

错架图书 **6**

馆藏状态错误 **6**

馆藏地错误 **0**

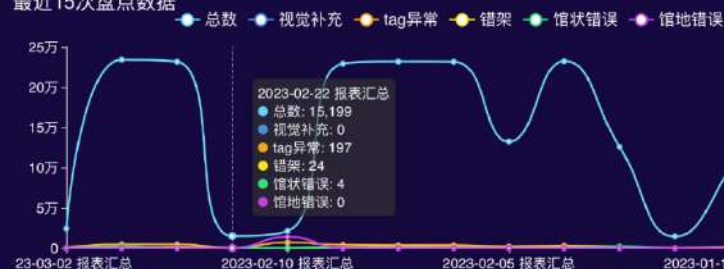
视觉补充 **0**



错架图书清单

序号

最近15次盘点数据



馆藏状态错误图书清单

序号

机器人指标



异常图书占比



错架图书占比

0

书架个数

0

盘点耗时

# User Creation and Management

报表管理平台

图客超管

Home

Robot

Library

Report Data

Visualization Add

Visualization

Account

Account Add

Account List

Account

## 用户列表

昵称:

角色:

Reset

Query


Expand

序号	账号	昵称	角色	组织	状态	操作
1	admin	图客超管	admin	江苏图客机器人有限公司	正常	<a href="#">修改</a> <a href="#">禁用</a> <a href="#">删除</a>
2	dev1	图客账号	图客管理员	江苏图客机器人有限公司	正常	<a href="#">修改</a> <a href="#">禁用</a> <a href="#">删除</a>
3	dev2	图客账号	图客管理员	江苏图客机器人有限公司	已禁用	<a href="#">修改</a> <a href="#">启用</a> <a href="#">删除</a>
4	dev3	图客账号	图客管理员	江苏图客机器人有限公司	正常	<a href="#">修改</a> <a href="#">禁用</a> <a href="#">删除</a>
5	pro1	图客账号	图客管理员	江苏图客机器人有限公司	正常	<a href="#">修改</a> <a href="#">禁用</a> <a href="#">删除</a>
6	pro2	图客账号	图客管理员	江苏图客机器人有限公司	正常	<a href="#">修改</a> <a href="#">禁用</a> <a href="#">删除</a>
7	pro3	图客账号	图客管理员	江苏图客机器人有限公司	正常	<a href="#">修改</a> <a href="#">禁用</a> <a href="#">删除</a>
8	pro4	图客账号	图客管理员	江苏图客机器人有限公司	正常	<a href="#">修改</a> <a href="#">禁用</a> <a href="#">删除</a>

# Robot Screen UI – Main Screen



 Home Page

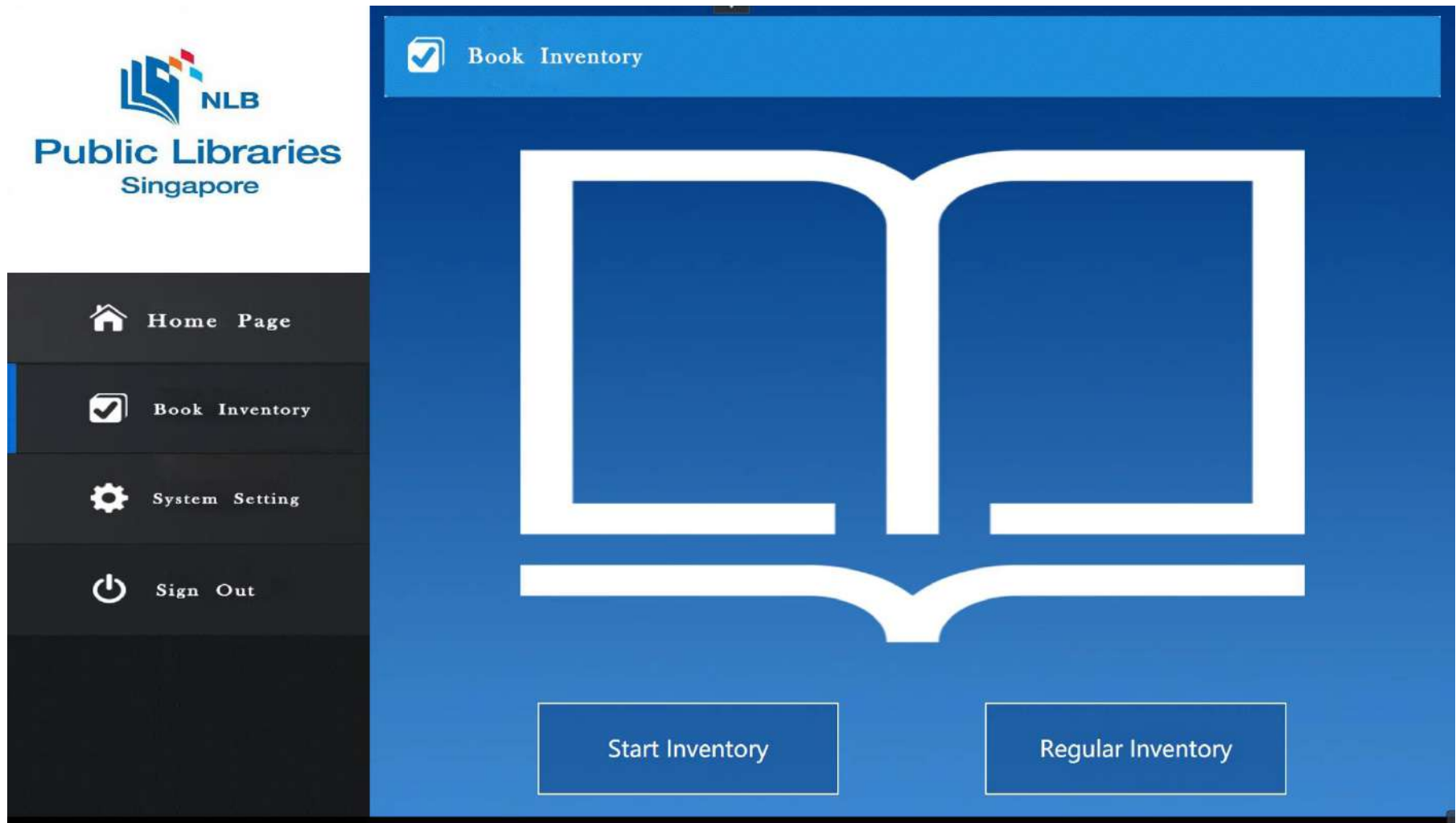
 Book Inventory

 System Setting

 Sign Out

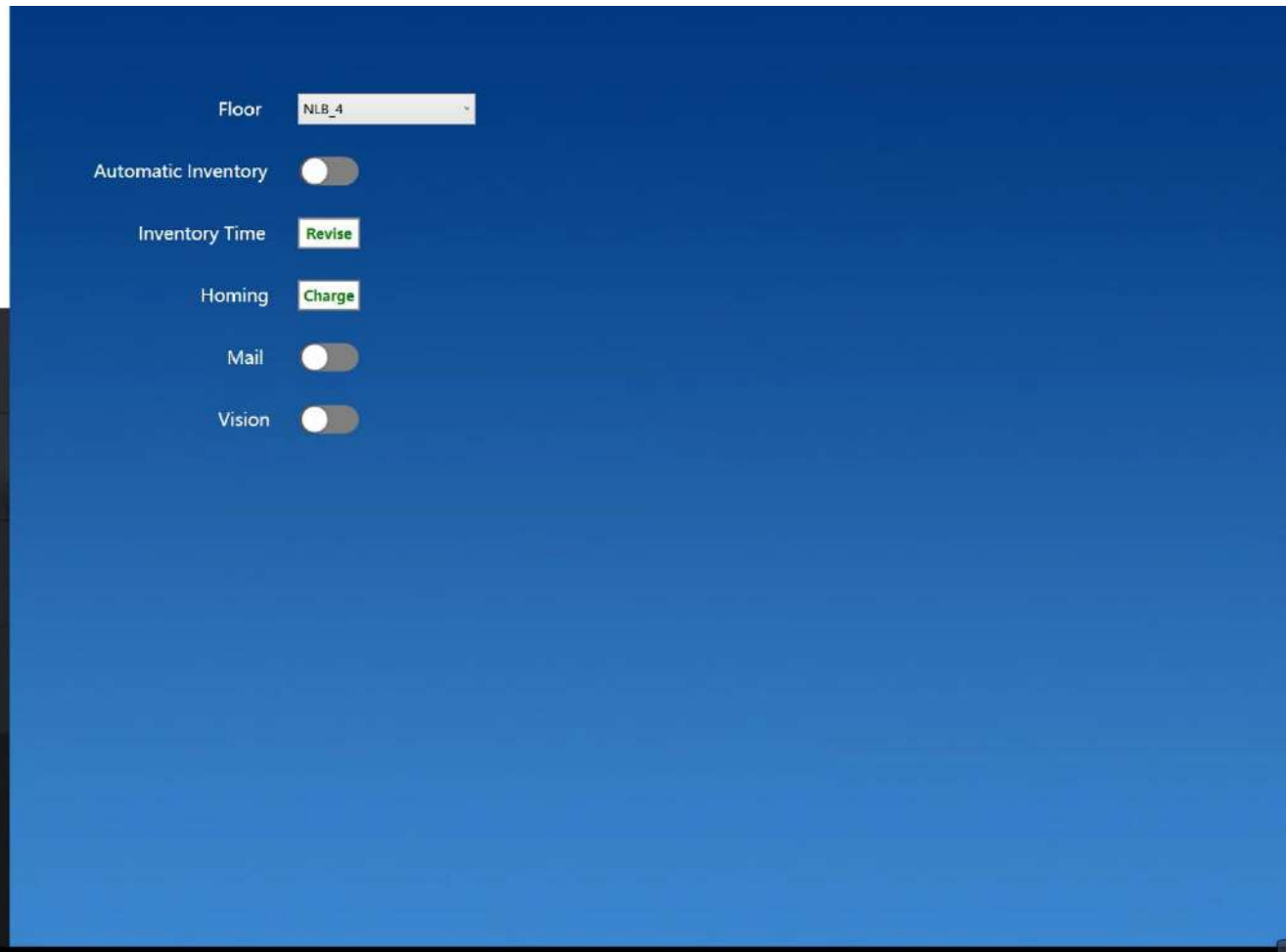
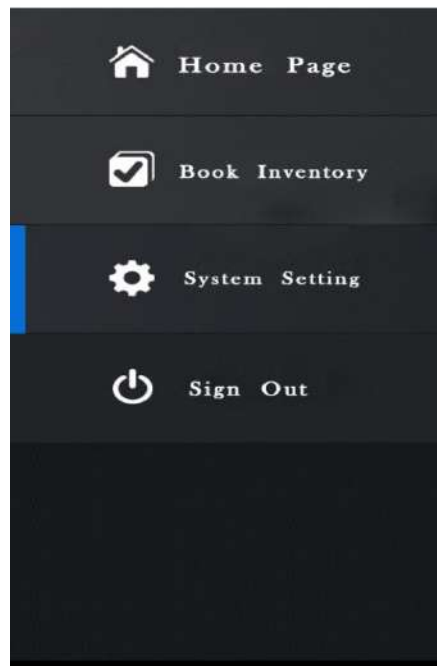


# Robot Screen UI – Book Inventory





# Robot Screen UI – System Setting



# Books Detection and Location Report - Sample

Barcode	Call number	Level	Detected location	Detected Location	Date	Remarks
B37558002H	AAA	4	01架A面01列01层	S1-T1-B1	2023-03-06 09:48:57.677819	
B37558003I	AAB	4	01架A面01列01层	S1-T1-B1	2023-03-06 09:48:57.648781	
B37558005K	AAC	4	01架A面01列01层	S1-T1-B1	2023-03-06 09:48:57.425844	
B37558006A	AAD	4	01架A面01列01层	S1-T1-B1	2023-03-06 09:48:57.735128	
B37558007B	AAE	4	01架A面01列01层	S1-T1-B1	2023-03-06 09:48:57.672849	
B37558008C	AAF	4	01架A面01列01层	S1-T1-B1	2023-03-06 09:48:57.640787	
B37558010G	AAG	4	01架A面01列01层	S1-T1-B1	2023-03-06 09:48:57.642191	
B37558011H	AAH	4	01架A面01列01层	S1-T1-B1	2023-03-06 09:48:57.639388	
B37558012I	AAI	4	01架A面01列01层	S1-T1-B1	2023-03-06 09:48:57.174918	
B37558013J	AAJ	4	01架A面01列01层	S1-T1-B1	2023-03-06 09:48:57.994616	
B37558014K	AAK	4	01架A面01列01层	S1-T1-B1	2023-03-06 09:48:57.982124	
B35602031I	ADI	4	01架A面01列01层	S1-T1-B1	2023-03-06 09:48:55.619000	
B33346773C	AIC	4	01架A面01列01层	S1-T1-B1	2023-03-06 09:48:56.770000	
B33200961B	ALE	4	01架A面01列01层	S1-T1-B1	2023-03-06 09:48:56.388000	
B37557960I	ALS	4	01架A面01列01层	S1-T1-B1	2023-03-06 09:48:57.528000	
B30612744E	AND	4	01架A面01列01层	S1-T1-B1	2023-03-06 09:48:55.994000	

# Books Misplaced Report - Sample

Barcode	Call number	Level	Detected location	Detected Location	Date	Remarks
B37558015A	AAL	4	01架A面01列02层	S1-T2-B1	2023-03-06 09:48:58.989446	Misplaced books
B37558016B	AAM	4	01架A面01列02层	S1-T2-B1	2023-03-06 09:48:57.999307	Misplaced books
B37558017C	AAN	4	01架A面01列02层	S1-T2-B1	2023-03-06 09:48:57.993046	Misplaced books
B37558018D	AAO	4	01架A面01列02层	S1-T2-B1	2023-03-06 09:48:57.676271	Misplaced books
B37558019E	AAP	4	01架A面01列02层	S1-T2-B1	2023-03-06 09:48:57.665681	Misplaced books
B37558020H	AAQ	4	01架A面01列02层	S1-T2-B1	2023-03-06 09:48:57.970285	Misplaced books
B37558021I	AAR	4	01架A面01列02层	S1-T2-B1	2023-03-06 09:48:58.589839	Misplaced books
B37558022J	AAS	4	01架A面01列02层	S1-T2-B1	2023-03-06 09:48:57.170636	Misplaced books
B37558023K	AAT	4	01架A面01列02层	S1-T2-B1	2023-03-06 09:48:57.161247	Misplaced books
B31741917K	BUR	4	01架A面01列02层	S1-T2-B1	2023-03-06 09:48:18.820000	Misplaced books
B37558031J	DDA	4	01架A面01列03层	S1-T3-B1	2023-03-06 09:49:59.264939	Misplaced books
B37558032K	DDB	4	01架A面01列03层	S1-T3-B1	2023-03-06 09:49:59.326070	Misplaced books
B37558033A	DDC	4	01架A面01列03层	S1-T3-B1	2023-03-06 09:48:29.963784	Misplaced books
B37557840F	GGA	4	01架A面02列03层	S1-T3-B2	2023-03-06 09:49:02.673883	Misplaced books

## Honors and Awards



### APPLIED FOR OVER 50 DOMESTIC & FOREIGN PATENTS

Possesses complete independent intellectual property rights.

### THE NATIONAL STANDARD LED BY THE TEAM HAS BEEN APPROVED FOR IMPLEMENTATION

"General Technical Conditions for Library Inventory Robots."



- The highest award in the 46th Geneva International Invention Exhibition: **The Special Gold Award**
- The highest award, for Outstanding Exhibits in the University Exhibition Area at the 22<sup>nd</sup> China International Industry Fair: **The Special Prize**
- Awarded the title of **"2020 China Good Technology"** by the China Productivity Promotion Center Association.
- Selected as one of the **"Top 10 Technological Advances in World Intelligent Manufacturing in 2022"** by the Intelligent Manufacturing Alliance of CAST Member Societies (IMAC)





Thank You !